
Knowledge Aided Clutter Prediction And Comparison With Measured Data

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Advanced Programs

Outline

- Simulation Capabilities for Predictive Modeling
 - Simulation Performance Verification
 - Radar/Clutter Simulation and Modeling Capabilities
 - Current Hardware Test Equipment and Facilities
 - Future Development of SAR Laboratory
 - Problems for Laboratory Investigation
 - Problems for Investigation and Solution Development
 - Evaluation of Clutter Mitigation Methods
 - Knowledge Assisted Processing
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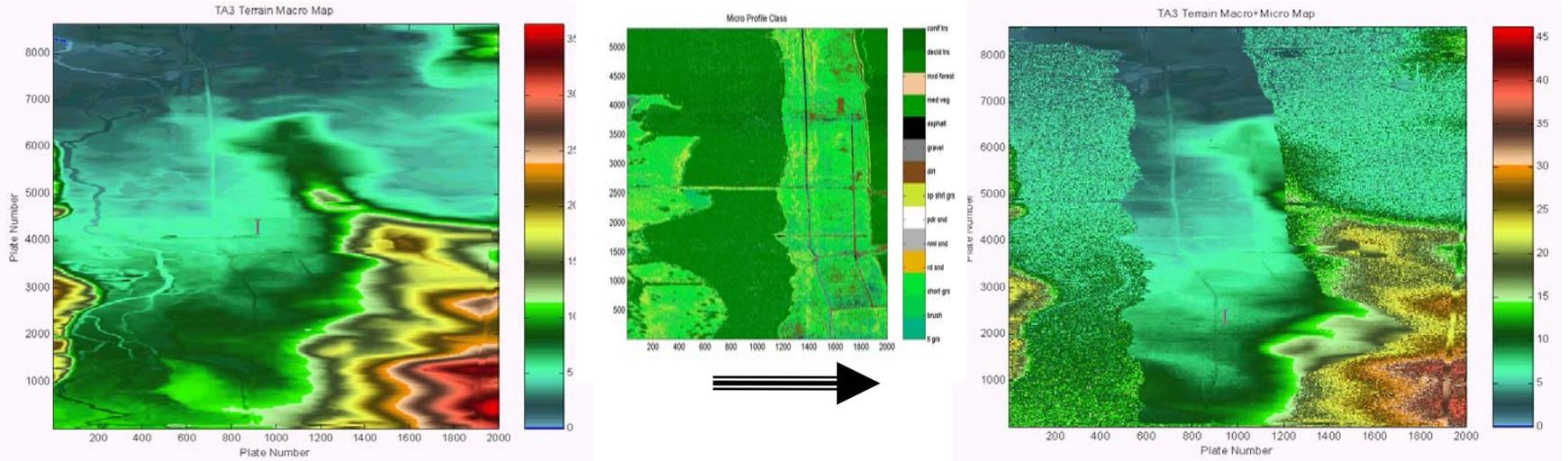
Simulation Capabilities for Predictive Modeling

- Raytheon Has Developed a High Fidelity Simulation Program to Predict the Performance of Pulse-Doppler and SAR Systems
 - The Simulation Allows the User to Define the Important Platform and Sensor Parameters Through an Easy to Use Graphical Interface
 - Internal Physical Models
 - Physical Optics Based Ray-Trace Algorithms
 - Polarization
 - Meteorological Effects
 - Detailed Facet Models
 - Vehicles (Tanks, Trucks, SAM Battery, Etc.)
 - Foliage (Trees, Shrubs, Grasses, Etc.)
 - People (Soldiers with Various Types of Equipment)
 - Clutter Calculations
 - DTED (Any Level)
 - DFAD (28 Surface Types)
 - Limited Set of Cultural Databases
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Simulation Performance Verification

- MMW ISAR Measurements for a T72 Tank Target and MSTAR Model Data set
 - Model Differed from Actual Tank
 - Surface Details were Missing from Model (Tread Fenders, Small Protrusions)
 - Surface Material was Modeled as Perfect Conductor
 - Correlation Values of 50-70% Required for ATA/ATR
 - Significantly Better than Equivalent X-Patch Results
 - Clutter Predictions
 - Compared Simulated Data to MIT/LL (Billingsly) Measurements for Cochrane, Alberta Canada
 - Tall Grass Features
 - DTED Level 1 Topographic
 - Fixed Radar Scans
 - Clutter σ_0 Mean and Probability Density Function Compared Favorably Between MIT/LL Measurements (Repeat Sector) and TKMOD
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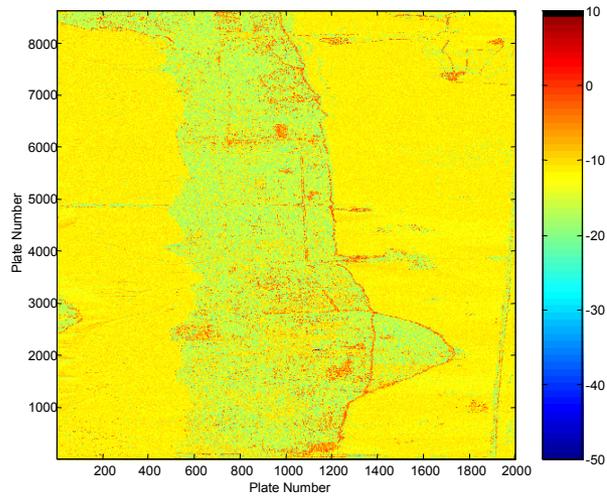
Simulation Clutter Model Generation Examples



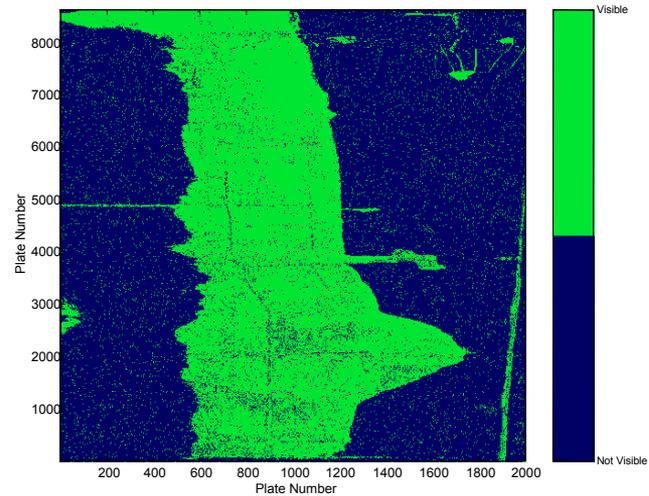
DTED Macro Map

Micro Structures

Terrain Macro+Micro Map

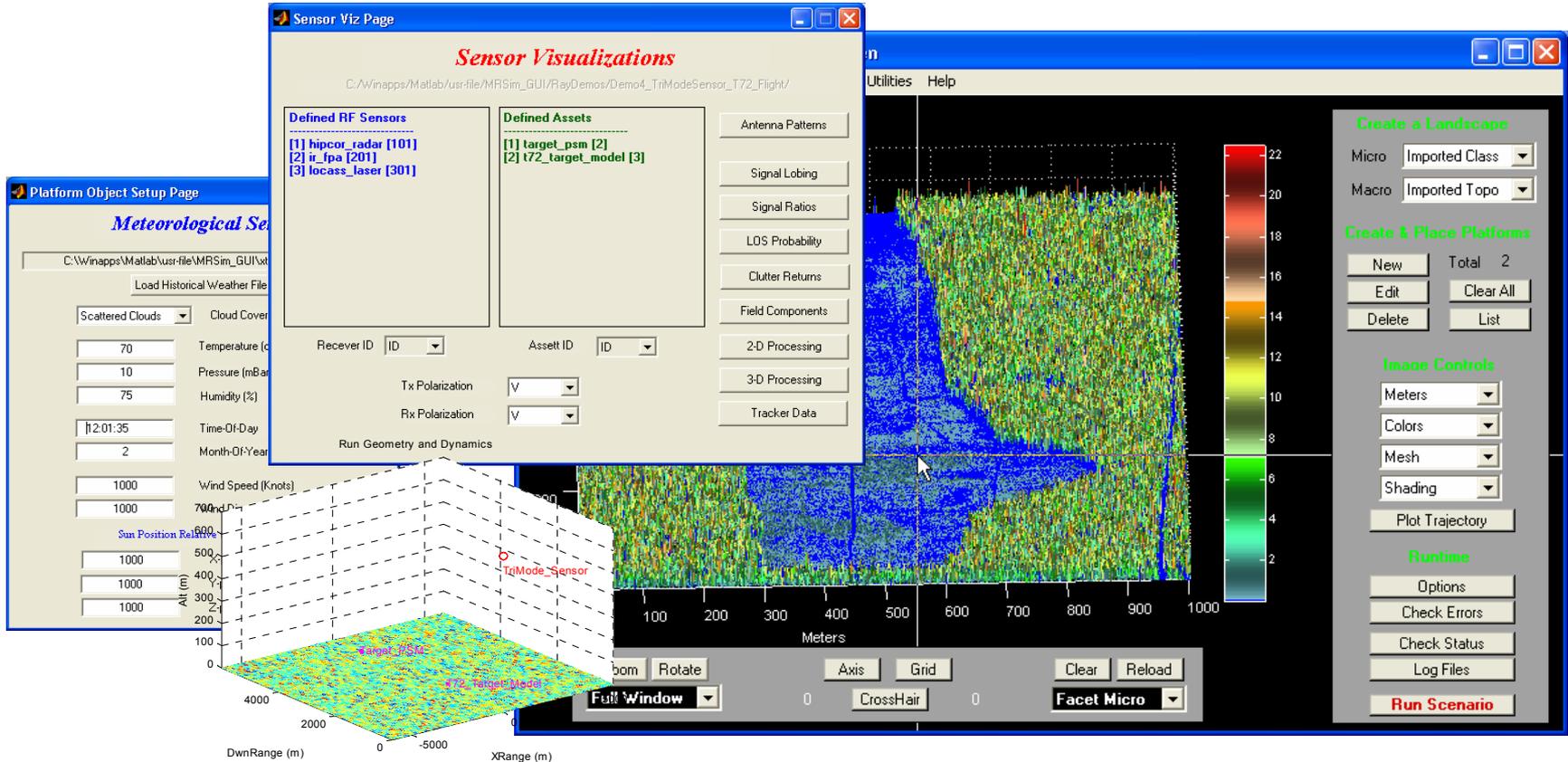


Computed Clutter Map



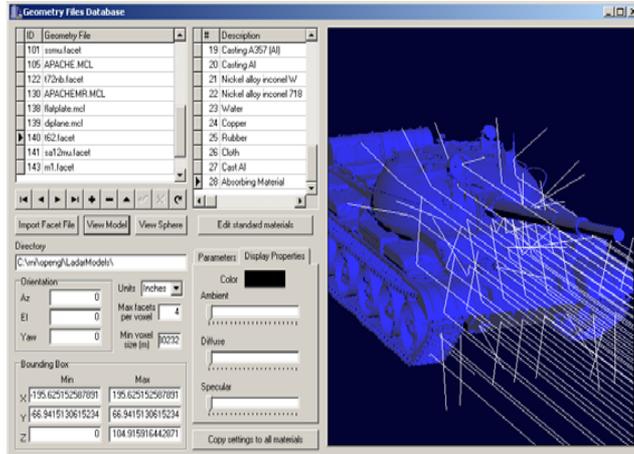
LOS Overlay Map

Radar/Clutter Simulation User Interface

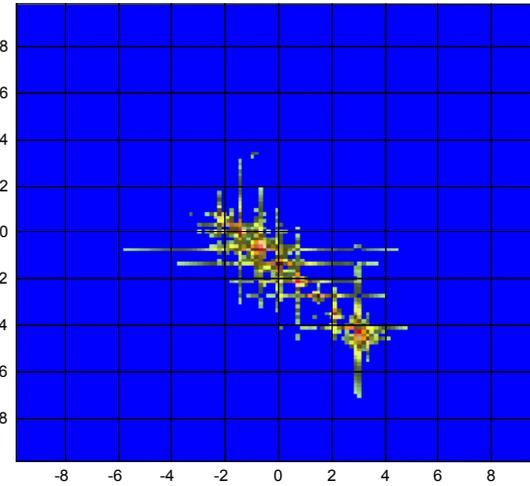


- Provides Parameter Setups and Output Visualizations (Including In-Process)
- Includes a Number of Utilities for Data Visualization and Virtual Prototyping

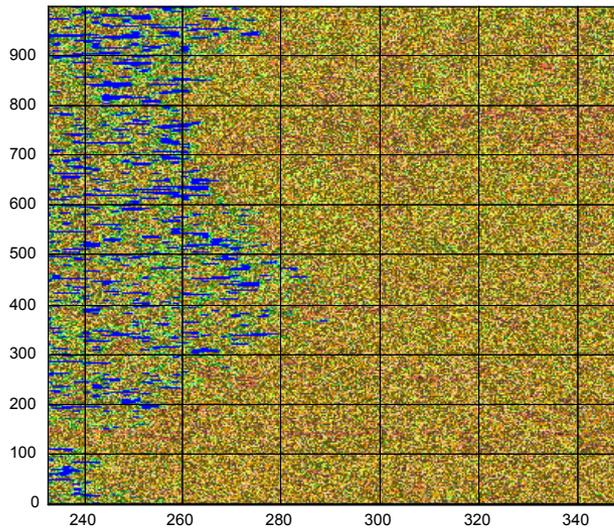
SAR Components: Target Selection & Scene Combination



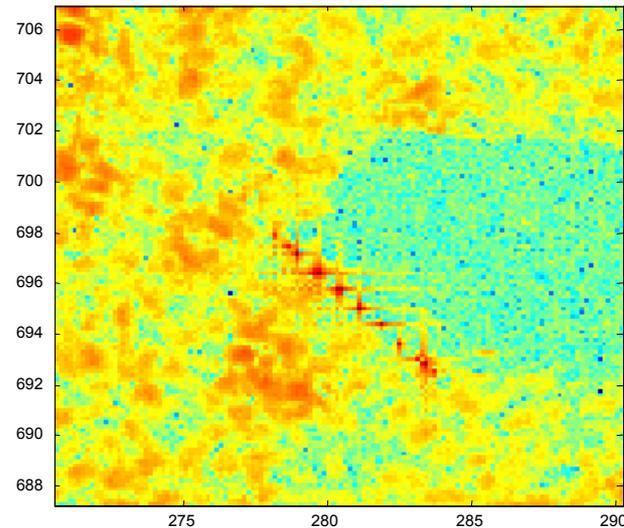
GUI Target Model Selection



Calculated Target RCS



Processed Scene Imagery



Combined Image, Target, and Additive Noise

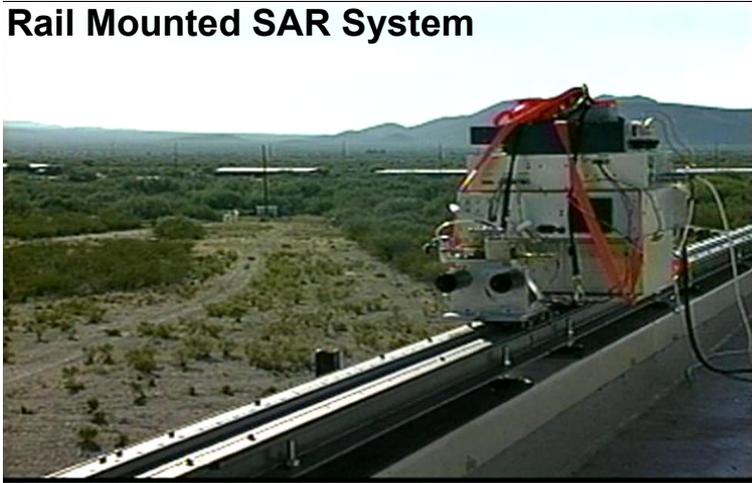
Current Hardware Test Equipment and Facilities

- The Raytheon Tucson, AZ Site has Built a Rooftop SAR Rail Test and Development Facility
 - Located on a Building Adjacent to a Semi-Desert Area
 - Terrain Elevation Standard Deviation ~ 1m
 - Natural Vegetation: Mesquite, Cactus, Small Leafed Trees
 - Features Include Fences, Poles, Corner Reflectors, Nearby Highway
 - Sensor Motion
 - Produced by Wheeled Motor Assembly on Permanently Attached Rail Track
 - Position, Orientation, and Velocity are Monitored and Recorded
 - Radar is a Ka-Band Monopulse T/R Module
- SAR Observation Ground Patch
 - Primary Site is Located 300m from Radar System
 - Effective Patch Area is Approximately 40m x 40m
 - Small SAR Image Cell Area

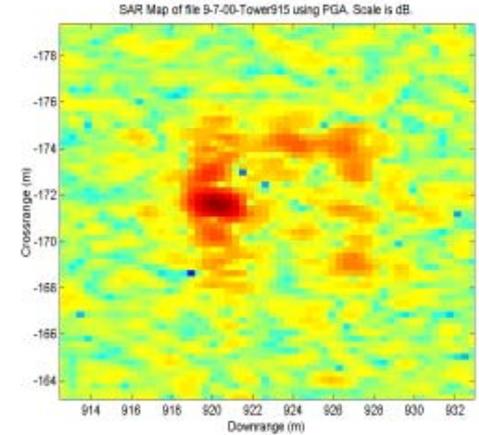
Laboratory Advantages: Repeatability, Reproducibility, Cost, Time

Rooftop SAR Facility and Sample SAR Images

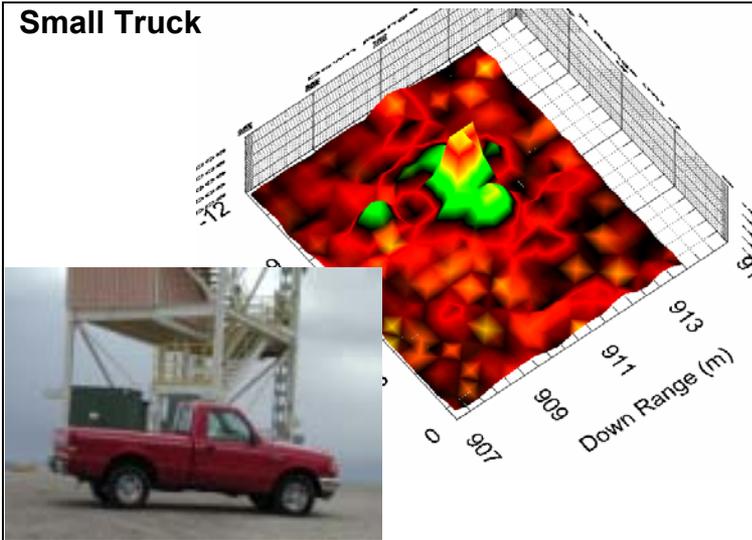
Rail Mounted SAR System



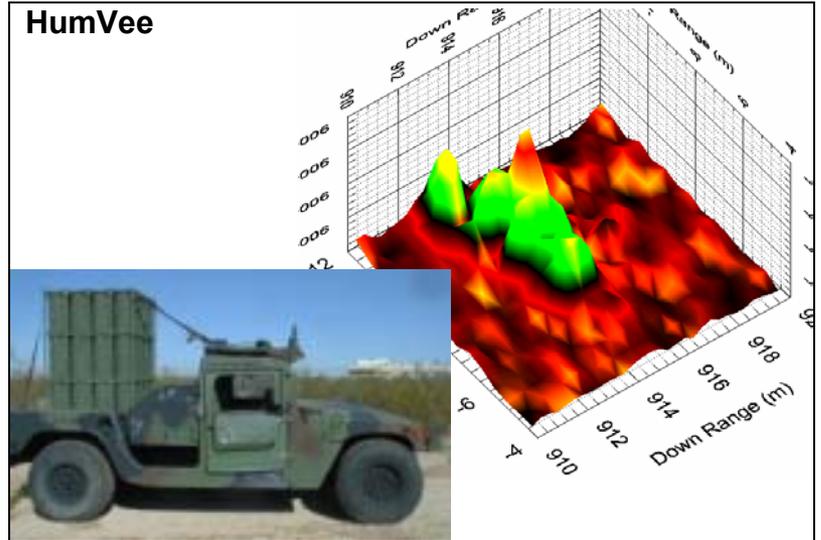
RF Tower



Small Truck



HumVee



Future Development of SAR Laboratory

- Verify Radar/Clutter Simulation Results
 - Initially with Very Accurate Survey Data
 - Comparisons of Results with DTED and DFAD Only Information
 - Measurements Performed in Various Non-Uniform Terrain Areas
 - Move The Current Instrumentation to Nearby Mountain Sites Overlooking Regions of Rugged Terrain
 - Develop of Next Generation Test Systems
 - Other Frequency Bands
 - Different Types of Transmitter/Receiver Equipment
 - Multichannel Receiver Arrays
 - DPCA / ADPCA
 - Along-Track Interferometric SAR
 - Improved Sensor Platforms
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Problems for Laboratory Investigation

- Comparisons of Measured and Modeled Target / Clutter Signals
 - Determine Differences Under Controlled Repeatable Conditions
 - Evaluate Reasons for Significant Differences
 - Verify and Improve Radar/Clutter Simulation Models
 - Investigate Hardware/Software Tradeoffs
 - Improved Measurement Accuracy:
 - Transmitter and Receiver Stability
 - Kinematics Determination Using Differential GPS/INS
 - Adaptive Signal Processing Methods for Error Estimation and Reduction
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Evaluation of Clutter Mitigation Methods

- Waveforms
 - Multiple Resolution
 - Target Adaptive
 - Time Reversal Focusing
 - Radar Signal Precursors
 - Raytheon Developed Adaptive DPCA Processing
 - Model Calculations Predict Clutter Cancellation Reduction
 - Limited Test Results Have Demonstrated Predicted Clutter Cancellation
 - Along-Track Interferometry for Direct Velocity Measurements
 - Coherent Change Difference of Sequential SAR Images
 - Polarization Variations
 - Circular
 - Dual Linear Polarization (HH, VV, HV)
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Knowledge Assisted Processing

- Using DTED Only:
 - Improved Accuracy for SAR Image to Geographical Map Transformations
 - Identification of Shadow Regions
 - A Priori Motion Probability Maps to Aid Detection and Tracking
 - Identification of Open Continuous Regions that can be Used for Roads
 - Identification of Areas Containing Rugged Terrain Unlikely to Contain Movers
 - Using the Clutter Simulation with DTED, DFAD, Cultural, and Meteorological Databases
 - Intelligent Secondary Covariance Matrix Sample Selection
 - Deterministic Nulling of Discrete Clutter
 - Quantify Performance Improvement for Different Scenario Conditions
 - Terrain
 - Urban / Rural Locations
 - Meteorological
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